



SERIAL1_BAUD	115	57	1 1200 2 2400 4 4800 9 9600 19 19200 38 38400 57 57600 115 115200 135 135000 230 230400 456 456000 462 462000 924 924000 921 921600 1842 1842000 3000 300000	The baud rate used on the Telem1 port. Most stm32-based boards can support rates of up to 1500. If you set up a rate you cannot support and then can't connect to your board you should load a firmware from a different vehicle type. That will reset all your parameters to default.	■	
SERIAL1_PROTOCOL	1	2	1 Name 1 MAVLink 2 MAVLink2 3 Name 04 Sata Serial 4 ESC 7 Phoenix Central Serial 8 Combot 9 Banguanther 10 OpenTX 11 Lidar360 12 Banguanther 13 OpenTX 14 15 Blue series out 16 ESC 17 Telemetry 18 Telemetry 19 Coppalchew 19 RoboticsServo 20 MEG Output 21 MicroSwarm 22 LIDAR 23 FCIn 24 EPI Serial 25 STM 26 SBus 27 Inertial 28 SBus 29 SBus 30 SBus 31 SBus 32 SBus 33 SBus 34 SBus 35 SBus 36 SBus 37 SBus 38 SBus 39 SBus 40 SBus 41 SBus 42 SBus 43 SBus 44 SBus 45 SBus 46 SBus 47 SBus 48 SBus 49 SBus 50 SBus 51 SBus 52 SBus 53 SBus 54 SBus 55 SBus 56 SBus 57 SBus 58 SBus 59 SBus 60 SBus 61 SBus 62 SBus 63 SBus 64 SBus 65 SBus 66 SBus 67 SBus 68 SBus 69 SBus 70 SBus 71 SBus 72 SBus 73 SBus 74 SBus 75 SBus 76 SBus 77 SBus 78 SBus 79 SBus 80 SBus 81 SBus 82 SBus 83 SBus 84 SBus 85 SBus 86 SBus 87 SBus 88 SBus 89 SBus 90 SBus 91 SBus 92 SBus 93 SBus 94 SBus 95 SBus 96 SBus 97 SBus 98 SBus 99 SBus 100 SBus	Control what protocol to use on the Telem1 port. Note that the Frsky options require external converter hardware. See the wiki for details.	■	
SRI_EXTRA1	50	1	Hz	0.50	MAVLink Stream rate of ATTITUDE_SIMSTATE (SIM only), AHR52, RPM, ADA_SSA, LAMING_ESC, TELEMETRY_EP_S, DRIS, and PD, TLWING	■
SRI_RC_CHAN	50	1	Hz	0.50	MAVLink Stream rate of SERVO_OUTPUT_PWM and RC_CHANNELS	■